

Neural Networks & Gradient Descent

Plan:

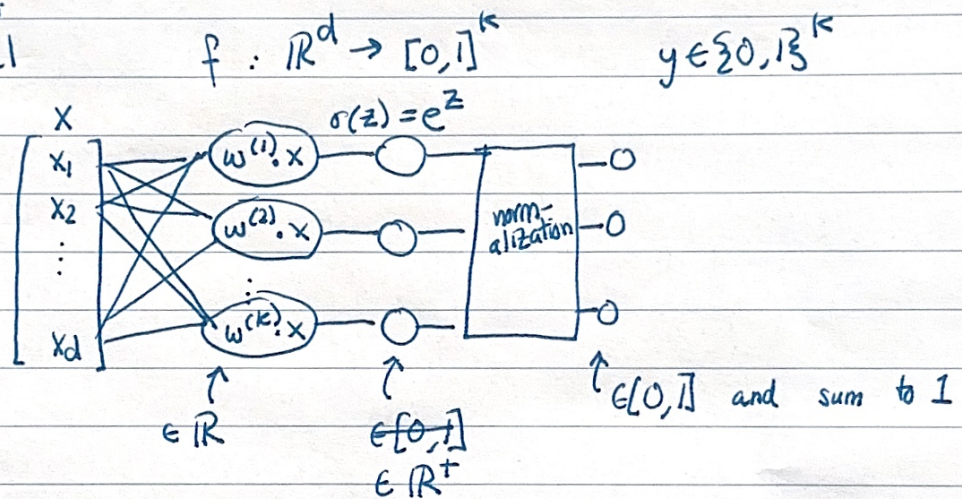
- Review
- Neural Networks
- Gradient Descent
- Backpropagation

Logistics:

- Zoom in
- scribed notes (moved by 2)

Review:

① Model

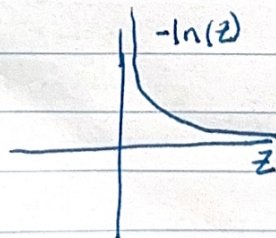


② Loss: Cross Entropy

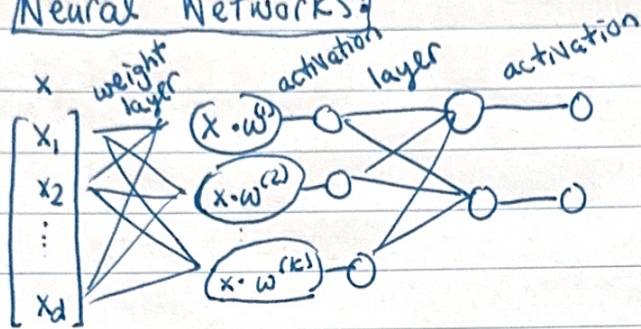
$$H(y, f(x)) = - \sum_{i=1}^k y_i \log f(x)_i = - \log f(x)_i^*$$

+ efficient

+ big gradient if $f(x)_i^* \approx 0$



Neural Networks:



Activation functions

Sigmoid	$\frac{1}{1+e^{-z}}$
ReLU	$\max(0, z)$
step	$\mathbb{1}[z > 0]$
sign	$\mathbb{1}[z > 0] - \mathbb{1}[z < 0]$

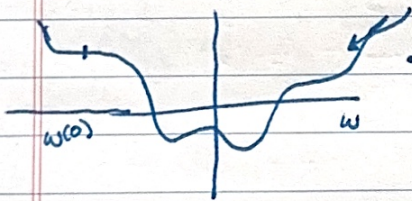
$$Wx = \begin{bmatrix} w^{(1)} \\ w^{(2)} \\ \vdots \\ w^{(k)} \end{bmatrix} \begin{bmatrix} x \\ x \\ \vdots \\ x \end{bmatrix} = \begin{bmatrix} w^{(1)}x \\ w^{(2)}x \\ \vdots \\ w^{(k)}x \end{bmatrix}$$

$k \times d$

Layers

- ↳ Dense / fully connected
- ↳ Convolutional : images or spatial data
- ↳ Recurrent : sequential data
- ↳ Residual : processing technique
- ↳ Attention : sequential data with short + long dependencies

Gradient Descent:



• Initialize $w^{(0)}$

• Iteratively improve loss

$$w^{(t+1)} \leftarrow w^{(t)} - \alpha \nabla_w L(w)$$

- small α "guarantees" improvement but slowly
- big α moves quickly but can overshoot

Activity 3

Gradient descent on linear regression

$$w^{(t+1)} \leftarrow \underline{\hspace{10em}}$$

Time complexity of optimal solution:

Time complexity of one update:

Stochastic Gradient Descent

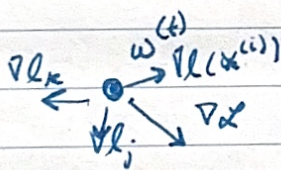
$$L(w) = \frac{1}{n} \sum_{i=1}^n l_i(x^{(i)}, y^{(i)}, w)$$

← expensive! fit in memory?

$$S \subseteq [n]$$

$$w^{(t+1)} \leftarrow w^{(t)} - \alpha \frac{1}{|S|} \sum_{i \in S} \nabla_w l_i(x^{(i)}, y^{(i)}, w)$$

Trade off: speed for "representativeness"



Back propagation

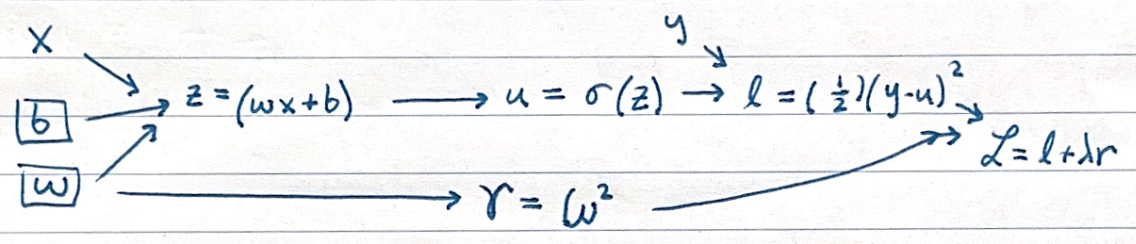
$$\mathcal{L}(w, b) = \frac{1}{2} (y - \sigma(wx+b))^2 + \lambda w^2$$

regularization on size of w = "complexity"

$$\frac{\partial \mathcal{L}}{\partial w} = (y - \sigma(wx+b)) \cdot \sigma'(wx+b) \cdot x + 2\lambda w$$

$$\frac{\partial \mathcal{L}}{\partial b} = (y - \sigma(wx+b)) \cdot -\sigma'(wx+b) \cdot 1$$

Redundancy! Complicated!

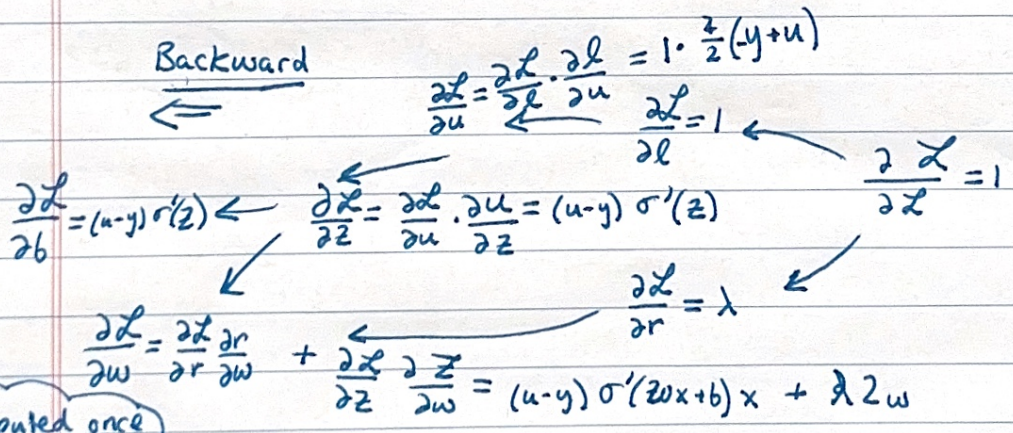


Forward



for $i \in \{1, \dots, N\}$:
compute v_i as function of parents

Backward



+ computed once
+ structured
+ modular

for $i \in \{1, \dots, N\}$:

$$\text{compute } \frac{\partial \mathcal{L}}{\partial v_i} = \sum_{j \in \text{children}(v_i)} \frac{\partial \mathcal{L}}{\partial v_j} \frac{\partial v_j}{\partial v_i}$$